

General Mechanics of Continua

→ An Introduction

- refs:
- Goldstein, chapter posted
 - Whitham }
- Lighthill } see ref. list
 - Stone article, posted
 - F&W.

1

f.) More Oscillations : Mechanics of Fields

→ recall the ~~discrete~~ string : (i.e continuum limit)

$\mathcal{L} = \mathcal{L}(y, y_t, y_x) \rightarrow$ Lagrangian density

$$\mathcal{L} = \frac{1}{2} \mu y_t^2 - T \left[(1 + y_x^2)^{\frac{1}{2}} - 1 \right] \quad \begin{matrix} (1D) \\ \equiv \\ \text{potential energy in string} \end{matrix}$$

where $S = \int_{t_1}^{t_2} dt \int_0^L dx \mathcal{L}$ t, x both parameters

Then, for EoM : $\delta S = 0$ (as usual)

$$\begin{aligned} \delta S = 0 &= \int_{t_1}^{t_2} dt \int_0^L dx \left(\frac{\partial \mathcal{L}}{\partial y} dy + \frac{\partial \mathcal{L}}{\partial y_t} dy_t + \frac{\partial \mathcal{L}}{\partial y_x} dy_x \right) \\ &= \int_{t_1}^{t_2} dt \int_0^L dx \left(\frac{\partial \mathcal{L}}{\partial y} dy + \frac{\partial \mathcal{L}}{\partial y_t} \frac{dy}{dt} dt + \frac{\partial \mathcal{L}}{\partial y_x} \frac{dy}{dx} dx \right) \\ &= \int_0^L dx \left. \frac{\partial \mathcal{L}}{\partial y} \right|_{t_1}^{t_2} + \int_{t_1}^{t_2} dt \left. \frac{\partial \mathcal{L}}{\partial y_x} \right|_0^L \\ &\quad + \int_{t_1}^{t_2} dt \int_0^L dx \left(\frac{\partial \mathcal{L}}{\partial y} - \frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial y_t} \right) - \frac{d}{dx} \left(\frac{\partial \mathcal{L}}{\partial y_x} \right) \right) dy \end{aligned}$$

fixed
end pts
in time!
&
no config
change.

thus, have Lagrange EOM:

$$\frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{x}_t} \right) = \frac{\partial \mathcal{L}}{\partial y} - \frac{d}{dx} \left(\frac{\partial \mathcal{L}}{\partial y_x} \right)$$

with B.C. : $\left. \frac{\partial \mathcal{L}}{\partial y_x} \right|_0^L = 0$

(clear for
fixed, free
ends)

A.b : → have

- optional b.p. endpt.

$$\left. \int_{t_i}^{t_2} \frac{\partial \mathcal{L}}{\partial y_x} dy \right|_0^L$$

- $y(t, x) = 0$, all x , only at t_2, t_1 .

→ in 3D, have:

$$\frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{x}_i} \right) = \frac{\partial \mathcal{L}}{\partial y} - \frac{d}{dx_i} \left(\frac{\partial \mathcal{L}}{\partial x_i} \right)$$

→ for 1D string:

$$\frac{d}{dt} (u y_t) = \frac{d}{dx} \left(\frac{T y_x}{(1+y_x^2)^{3/2}} \right)$$

3. ~~scribble~~

small oscillations: $\mathcal{L} = \frac{1}{2} u y_t^2 - \frac{1}{2} (y_x^2)$

$u y_{t,+} = T y_{xx} \rightarrow$ for a given variety
of wave eqn.

→ Ex. $U(\phi) = \alpha \frac{\phi^3}{2} + \beta \phi^4$

$\mathcal{L} = \frac{\phi_t^2}{2} - \frac{(\nabla \phi)^2}{2} - U(\phi)$ Derive

⇒ EOM? \Rightarrow K-G Eqn.
 $\phi_{tt} = \phi_{xx} + \alpha \phi + \beta \phi^3 = 0$

Aside: Standard Problems

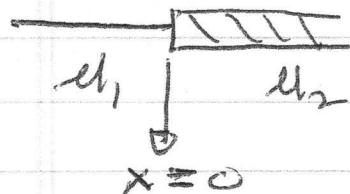
Now, Lagrangian formulation allows
unambiguous formulation of basic
equations for matching;

→ consider 3 prototypical examples

How to handle matching conditions?

4. ~~4~~

i.e.)



Junction

⇒ un-equal mass

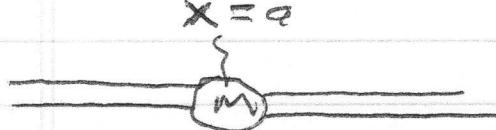
$$\text{matching} \Rightarrow y_{-(0)} = y_{+(0)}$$

$$\int_{0_-}^{0_+} \left\{ \frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial y_+} \right) - \frac{\partial \mathcal{L}}{\partial y} + \frac{d}{dx} \left(\frac{\partial \mathcal{L}}{\partial y_x} \right) \right\} = 0$$

i.e. integrate EoM

$$\left. \frac{\partial \mathcal{L}}{\partial y_x} \right|_{0_+} = \left. \frac{\partial \mathcal{L}}{\partial y_x} \right|_{0_-} \Rightarrow \text{slope match}$$

ii.)



(continuity
understood)

$$u \rightarrow u + M \delta(x-a)$$

$$\mathcal{L} = \frac{1}{2} (u + M \delta(x-a)) y_{++}^2 - \frac{T}{2} y_{xx}^2$$

$$(u + M \delta(x-a)) y_{++} = T y_{xx}$$

$$y = \tilde{y}(x) e^{-ict}$$

4a ~~4b~~

$$T\ddot{y}_{xx} = -\omega^2(u + M\delta(x-a))\dot{y}$$

$$\int_{a_-}^{a_+} [T\ddot{y}_{xx} + \omega^2(u + M\delta(x-a))\dot{y}] = 0$$

$$\hat{T} \dot{y}_x \Big|_{q_+}^{q_-} = -\omega^2 M y(s) \Rightarrow \text{jump condition}$$

\Rightarrow mass induces
geometry

N.B.: Use of Lagrangian ab-initio
renders all questions re: order
of derivatives moot.

Hamiltonian Formulation

Define canonical momentum:

$$\pi = \frac{\partial \mathcal{L}}{\partial \dot{y}} \rightarrow \pi \dot{y} \Rightarrow \begin{array}{l} \text{momentum} \\ (\text{in } y) \text{ of} \\ \text{string element} \end{array}$$

Can define Hamiltonian density:

$$\mathcal{H} = \pi \dot{y} - \mathcal{L}$$

$$H = \int \mathcal{H} dx$$

\hookrightarrow Hamiltonian.

$$\text{for } \frac{\partial \mathcal{L}}{\partial t} = 0, \mathcal{H} = \mathcal{E}$$

For string:

$$\stackrel{\text{kin E.}}{\downarrow} \quad \stackrel{\text{pot E}}{\rightarrow}$$

$$\mathcal{H} = \frac{\pi^2}{\mu} - \mathcal{L} = \frac{\pi^2}{2M} + T \sum y_x^2$$

So, as before, Hamilton's Equations for continua follow from Principle of Least Action:

$$\mathcal{S} = \int_{t_1}^{t_2} dt \int dx \left(\pi \dot{y} - \mathcal{H} \right)$$

$$\mathcal{L} = \mathcal{L} (\dot{y}, y_x, y)$$

$$\mathcal{H} = \mathcal{H} (\pi, y_x, y)$$

$$\mathcal{L} = \pi \dot{y} - \mathcal{H}$$

so

$$\delta \mathcal{S} = \int_{t_1}^{t_2} dt \int dx \left(\pi \delta \dot{y} + \dot{y} \delta \pi - \left(\frac{\partial \mathcal{H}}{\partial t} \delta t \right. \right. \\ \left. \left. + \frac{\partial \mathcal{H}}{\partial y_x} \delta y_x + \frac{\partial \mathcal{H}}{\partial y} \delta y \right) \right)$$

ignoring surface terms:

$$= \int_{t_1}^{t_2} dt \int dx \left\{ \dot{y} \delta \pi - \pi \delta \dot{y} - \frac{\partial \mathcal{H}}{\partial y} - \frac{\partial \mathcal{H}}{\partial t} \right. \\ \left. - \frac{\partial \mathcal{H}}{\partial y_x} \right\}$$

regrouping

L

$$\delta S = \int_{t_i}^{t_f} dt + \int_0^L dx \left\{ \frac{\partial \mathcal{L}}{\partial t} \left(\dot{x} + \frac{\partial \mathcal{H}}{\partial \dot{x}} \right) - \frac{d}{dx} \left(\frac{\partial \mathcal{H}}{\partial \dot{y}_x} \right) + \frac{\partial \mathcal{H}}{\partial x} \left(\dot{y} - \frac{\partial \mathcal{H}}{\partial \dot{x}} \right) \right\}$$

$$\text{so } \delta S = 0 \Rightarrow$$

$$\begin{cases} \dot{y} = \frac{\partial \mathcal{H}}{\partial \dot{x}} \\ \ddot{x} = -\frac{\partial \mathcal{H}}{\partial y} + \frac{d}{dx} \left(\frac{\partial \mathcal{H}}{\partial \dot{y}_x} \right) \end{cases}$$

Hamilton's
Eqs \rightarrow
motion of
elements
parametrized
by x, t .

$$\text{Now, } \frac{\partial S}{\partial t} = \frac{\partial \mathcal{H}}{\partial t} = 0 \text{ here}$$

$$\mathcal{H} = \pi \dot{y} - \mathcal{L}$$

$$\begin{aligned} \frac{d \mathcal{H}}{dt} &= \pi \ddot{y} + \dot{y} \pi \ddot{x} - \frac{d \mathcal{L}}{dt} \\ &= \pi \ddot{y} + \dot{y} \ddot{x} - \left(\frac{\partial \mathcal{L}}{\partial x} + \frac{\partial \mathcal{L}}{\partial y} \dot{y} + \frac{\partial \mathcal{L}}{\partial \dot{y}} \ddot{y} \right. \\ &\quad \left. + (\partial \mathcal{L}/\partial y_x) \dot{y}_x \right) \end{aligned}$$

$$\text{but, } \pi = \frac{\partial L}{\partial \dot{y}}$$

so $\pi \dot{y}$ cancels $- (\frac{\partial L}{\partial \dot{y}}) \dot{y}$

\Rightarrow

$$\frac{dH}{dt} = \dot{\pi} \dot{y} - \left(\frac{\partial L}{\partial y} \dot{y} + \frac{\partial L}{\partial y_x} \dot{y}_x \right)$$

and from LEOM:

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{y}} \right) + \frac{d}{dx} \left(\frac{\partial L}{\partial y_x} \right) = \frac{\partial L}{\partial y}$$

so $\frac{\partial L}{\partial \dot{y}} = \pi$

$$\begin{aligned} \frac{dH}{dt} &= \dot{\pi} \dot{y} - \dot{y} \left(\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{y}} \right) + \frac{d}{dx} \left(\frac{\partial L}{\partial y_x} \right) \right) \\ &\quad - \frac{\partial L}{\partial y_x} \dot{y}_x \\ &= - \dot{y} \frac{d}{dx} \left(\frac{\partial L}{\partial y_x} \right) - \frac{\partial L}{\partial y_x} \frac{d}{dx} \dot{y} \end{aligned}$$

\Rightarrow so finally regrouping:

$$\frac{dH}{dt} + \frac{d}{dx} \left(j \frac{\partial \mathcal{E}}{\partial y_x} \right) = 0$$

What does it mean?

\rightarrow Here $H = \Sigma$

so above \Leftrightarrow

$$\frac{d\Sigma}{dt} + \frac{dS_x}{dx} = 0$$

$\Sigma \rightarrow$ excitation energy density

$S \rightarrow$ excitation energy density Flux!

check: $S_x = j \frac{\partial \mathcal{E}}{\partial y_x}$

$$= -j y_x T$$

$$\omega^2 = c^2 k^2$$

$$c^2 = T/y$$

$$y = A \sin(kx - \omega t)$$

$$= +A^2 k \omega T \cos^2(kx - \omega t)$$

$$= k \omega T A^2 \cos^2(kx - \omega t)$$

10.

$$\omega = ck$$

$$\underline{S_x} = \underline{\omega^2 T \underline{A}^2} = \underline{\omega^2 T c \underline{A}^2}$$

phase group velocity (dispersionless)

$$= c \underline{\epsilon} \rightarrow \text{energy density.}$$

\rightarrow wave energy density flux

so

$$\frac{\partial \underline{\epsilon}}{\partial t} + \frac{\partial S_x}{\partial x} = 0$$

$$S = c \underline{\epsilon} \rightarrow \text{yr } \underline{\epsilon}$$

Result is a "Poynting Thm." for string

In higher dims:

$$\partial_t \underline{\epsilon} + \underline{\nabla} \cdot \underline{S} = 0$$

1b ~~1b~~

Note:

→ Poynting thm. relates (local) wave energy density with wave energy density flux, i.e.

$$\frac{d\mathcal{H}}{dt} + \partial_x S_x = 0$$

→ Poynting thm. relates rate of energy change to wave energy density flux thru interval

i.e.

$$\begin{aligned}\frac{d}{dt} E &= \frac{d}{dt} \int_{x_1}^{x_2} \mathcal{H} dx = - \int_{x_1}^{x_2} \frac{\partial}{\partial x} S_x \\ &= -S_x \Big|_{x_1}^{x_2}\end{aligned}$$

→ Poynting thm. formed by expressing $\frac{d}{dt} \Sigma$ as $\nabla \cdot \mathbf{S}$, etc.

recall in E and M:

$$\nabla \times \underline{B} = \frac{4\pi}{c} \underline{J} + \frac{1}{c} \frac{\partial \underline{E}}{\partial t}$$

$$\nabla \times \underline{E} = -\frac{1}{c} \nabla B / \partial t$$

12. ~~scribble~~

but $\Sigma = E^2/8\pi + B^2/8\pi$

then $\left(\frac{\partial \underline{E}}{\partial t} = C \underline{\nabla} \times \underline{B} - 4\pi \underline{J} \right) * \cdot \underline{E}/4\pi$

$$\left(\frac{\partial \underline{B}}{\partial t} = -C \underline{\nabla} \times \underline{E} \right) \cdot \left(\underline{B}/4\pi \right)$$

→ local power dissipated.
Analogue for strong \underline{J}

$$\frac{\partial}{\partial t} \left(\frac{E^2 + B^2}{8\pi} \right) = -\underline{E} \cdot \underline{J} - \nabla \cdot \left(\frac{C}{4\pi} \underline{E} \times \underline{B} \right)$$

\downarrow
 S

der form Poynting thm. by considering time rate
of change of energy density.

→ Important to distinguish:

$$\underline{P} = u \dot{y} \hat{y} \equiv \text{canonical momentum} \quad (\text{particle})$$

→ momentum of string element $u \dot{y}(x, t)$, in \hat{y} direction

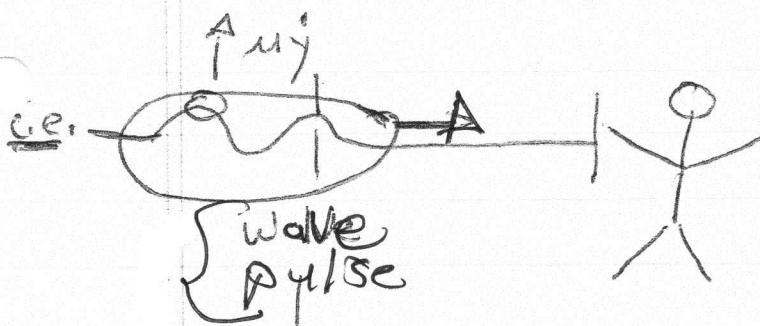
$$\underline{S} = -T \frac{\partial y}{\partial t} \frac{\partial \hat{x}}{\partial x} = \frac{\partial S}{\partial y} \frac{\partial y}{\partial t} \hat{x} \quad (\text{wave-particle})$$

≡ wave energy density flux

→ momentum of wave/fluctuation, in \hat{x} direction

13.

element



→ "feels" wave momentum
(kick in \vec{x})

$$\text{flux through } x = \underline{S_x(x, t)}$$

calculating for wave on string:

$$\text{if } y = A \cos(k(x - v_{ph}t))$$

$$v_{ph} = (T/\mu)^{1/2}$$

$$\frac{\partial y}{\partial t} = +A k v_{ph} \sin(k(x - v_{ph}t))$$

$$\frac{\partial y}{\partial x} = -A k \sin(k(x - v_{ph}t))$$

$$S_x = +T A^2 k^2 v_{ph} \sin^2(k(x - v_{ph}t))$$

$$\therefore \overline{S_x} = \frac{T k^2 v_{ph} A^2}{2}$$

$$\text{but: } \omega^2 = v_{ph}^2 k^2$$

$$\left\{ \overline{S_x} = \frac{\mu \omega^2 v_{ph} A^2}{2} \right\}$$

$$\overline{S_x} = v_{ph} E$$

$$\text{as } v_{ph} = v_{pr}$$

$$E = 2 * \overline{KE}$$

$$= 2 * \frac{1}{4} \mu \omega^2 A^2$$

14.

Wave Momentum Density

- have developed notions of wave energy and Poynting Theorem, i.e.
- natural to investigate wave momentum density

Now, recall in E&M,

$$P_{EM} = \frac{1}{c^2} S = \frac{1}{4\pi c} \underline{E} \times \underline{B} = \frac{1}{c^2} (\text{Wave Energy Density Flux})$$

\int momentum of electromagnetic wave \rightarrow Poynting vector

Thus, natural motivation to investigate relation for string, i.e.

$$\dot{P} = \ddot{y} \frac{\partial F}{\partial y_x}$$

so

$$\dot{F} = \ddot{y} \frac{\partial F}{\partial y_x} + \dot{y} \frac{d}{dt} \left(\frac{\partial F}{\partial y_x} \right)$$

for string:

$$\ddot{y} = \frac{T}{\mu} y_{xx} = V_{ph}^2 y_{xx} ; \quad \frac{\partial F}{\partial y_x} = -T y_x$$

15.

$$\begin{aligned}\dot{\mathcal{S}}_x &= \left\{ -\frac{T}{M} \dot{x} \times T \cdot \dot{x} - M \dot{y} \frac{T}{M} \dot{x} \right\} \\ &= -\frac{T}{M} \frac{\partial}{\partial x} \left\{ \frac{T}{2} \dot{x}^2 + \frac{M}{2} \dot{y}^2 \right\} \\ &= -C^2 \frac{\partial}{\partial x} \mathcal{E}\end{aligned}$$

then, have:

$$\frac{\partial}{\partial t} \mathcal{S}_x + C^2 \frac{\partial}{\partial x} \mathcal{E} = 0$$

so, if also EFM:

$$C^2 = T/M$$

$$P_w = \mathcal{S}/C^2$$

+
wave momentum
density

$$\Rightarrow \boxed{\frac{\partial}{\partial t} P_w + \frac{\partial}{\partial x} \mathcal{E} = 0}$$

in 1D

$$\left\{ \frac{\partial}{\partial t} P_w + \nabla_x \cancel{H} = 0 \right.$$

here $\nabla_x H = \nabla_x \Sigma$ is force density

$$P_w = \int_{x_1}^{x_2} dx \ P_w$$

pushes in
direction
of propagation

Momentum in
wave packet in
pulse of string $[x_1, x_2]$

so!

$$\frac{\partial}{\partial t} P_w = - \cancel{H} \int_{x_1}^{x_2}$$

difference / jump in energy density
across the chunk of string
 \Rightarrow net charge in WMD

Note:

- Semi-classical analogy

$$\Sigma = \omega \quad \varepsilon/\omega = N\omega$$

\hookrightarrow wave action density
(see next lecture)

$$\begin{aligned} P_w &= \frac{\Sigma}{c^2} = \frac{k}{\omega} \frac{c \varepsilon}{c} \\ &= \frac{k}{\omega} N \cancel{\omega} = kN \end{aligned}$$

Wave energy density $\rightarrow N\omega$

Wave momentum density $\rightarrow Nk$

$N \rightarrow$ # waves / wave propagation density,

iii) $m\dot{y} = \pi \rightarrow$ canonical momentum
 \uparrow direction

Now symmetry connection:

a) If string \oplus disturbance translated in \hat{x} and result invariant
 \Rightarrow conserved momentum,

8.

but

⑥ if disturbance/pulse translated
in x with string fixed, only
result in variant

\Rightarrow 3 conserved Pseudomomentum.

Evidently Pseudomomentum \leftrightarrow

Wave Momentum Density!

(a) Note can write:

$$\frac{\partial \Psi}{\partial t} + \frac{\partial S}{\partial x} = 0$$

$$\frac{\partial \rho_w}{\partial t} + \frac{\partial \Psi}{\partial x} = 0$$

$$\Rightarrow \left(\frac{1}{v_{ph}} \frac{\partial}{\partial t}, \frac{\partial}{\partial x} \right) \begin{bmatrix} \Psi & S/v_{ph} \\ S/v_{ph} & \epsilon \end{bmatrix} = 0$$

i.e. can think of:

$$\partial_{\mu} T^{\mu\nu} = 0$$

$T^{\mu\nu}$ = energy-momentum tensor
of string

$$T^{\mu\nu} = \begin{bmatrix} H & S/v_{ph} \\ S/v_{ph}, H \end{bmatrix}$$

$$\partial_{\mu} = (v_{ph} \partial_t, \partial_x)$$

For EM:

$$(E^2 + H^2)/8\pi$$

$$T^{0k} = \begin{pmatrix} \psi \\ 0 \\ S_x/c \\ S_y/c \\ S_z/c \end{pmatrix} = J$$

$$T_{\alpha\beta} = \frac{1}{4\pi} \left\{ -E_x E_0 - H_x H_0 \right. \\ \left. + \frac{S_x}{c} (E^2 + H^2) \right\}$$

Maxwell stress tensor.

→ Application: Sound

$$\frac{\partial}{\partial t} \rho + \underline{\nabla} \cdot (\rho \underline{v}) = 0$$

$$\frac{\partial}{\partial t} \underline{v} + \underline{v} \cdot \underline{\nabla} \underline{v} = - \frac{\partial \rho}{\partial p}$$

linearizing \Rightarrow

$$\frac{\partial \underline{v}}{\partial t} = - \frac{c_s^2}{\rho} \underline{\nabla} p$$

$$\begin{aligned} p &= A \rho \\ \frac{dp}{d\rho} &= c_s^2 \end{aligned}$$

$$\frac{\partial}{\partial t} \rho = - \rho \underline{\nabla} \cdot \underline{v}$$

then:

$$\frac{\partial^2}{\partial t^2} \rho = \rho \underline{\nabla} \cdot \left\{ \frac{c_s^2}{\rho} \underline{\nabla} p \right\} = c_s^2 \underline{\nabla}^2 \rho$$

$$\frac{\partial^2}{\partial t^2} \rho = c_s^2 \underline{\nabla}^2 \rho$$

\Rightarrow wave eqn.

~~2L~~

$$\text{then: } \frac{\partial^2 \hat{\rho}}{\partial t^2} = c_s^2 \nabla^2 \hat{\rho} = \rho \nabla \cdot \left\{ \frac{c_s^2}{\rho_0} \nabla \rho \right\}$$

For energy-momentum relations:

$$(1) \cdot \hat{V} \rho_0 + (2) \cdot \frac{\partial c_s^2}{\partial t} \hat{V} \cdot \nabla \hat{\rho}$$

$$\frac{\partial}{\partial t} \left(\frac{\rho_0 \hat{V}^2}{2} \right) + c_s^2 \cdot \lambda = 0$$

$$\frac{\partial}{\partial t} \left(\frac{\hat{\rho} c_s^2}{2 \rho_0} \right)^2 + c_s^2 \hat{\rho} \nabla \cdot \hat{V} = 0$$

$$\therefore \frac{\partial}{\partial t} \left(\frac{\rho_0 \hat{V}^2}{2} + \frac{\hat{\rho} c_s^2}{2 \rho_0} \right) + \nabla \cdot [c_s^2 \rho \hat{V}] = 0$$

$$H = E = \frac{\rho_0 \hat{V}^2}{2} + \frac{\hat{\rho}^2 c_s^2}{2 \rho_0}$$

$\frac{\partial}{\partial t}$
 $\downarrow T$
 $\downarrow V$
 \downarrow
 compression

elastic wave energy density flux

Similarly, fluid motion

$$\underline{\rho}_w = \frac{1}{c_s^2} \underline{S}$$

$$\frac{\partial \underline{\rho}_w}{\partial t} = \frac{\partial (\rho \underline{V})}{\partial t} = \frac{\partial \hat{\rho}}{\partial t} \hat{V} + \hat{\rho} \frac{\partial \underline{V}}{\partial t}$$

22.

$$\Rightarrow \frac{\partial \vec{v}}{\partial t} = -\rho_0 D \cdot \underline{v} \quad (1)$$

$$\frac{\partial \vec{p}}{\partial t} = -\frac{c_s^2}{\rho_0} \nabla p \quad (2)$$

~~cancel~~ $\underline{v} (1) + \vec{p} (2) \Rightarrow$

$$\begin{aligned} \frac{\partial (\tilde{\rho} \tilde{v})}{\partial t} &= -\rho_0 \underline{v} (D \cdot \underline{v}) - \frac{c_s^2}{2\rho_0} \nabla (\vec{p}^2) \\ &= -D \left(\frac{\partial \tilde{v}^2}{2} + \frac{c_s^2}{\rho_0} \frac{\partial \vec{p}^2}{2} \right) \end{aligned}$$

Momentum reflection for longitudinal linear waves.

$$\frac{\partial}{\partial t} \frac{\tilde{S}}{c_s^2} = -D \Sigma$$

$$= \frac{\partial}{\partial t} \underline{F}_w$$

{ ignored
all but
linear wave
energy }